

Fig. 1

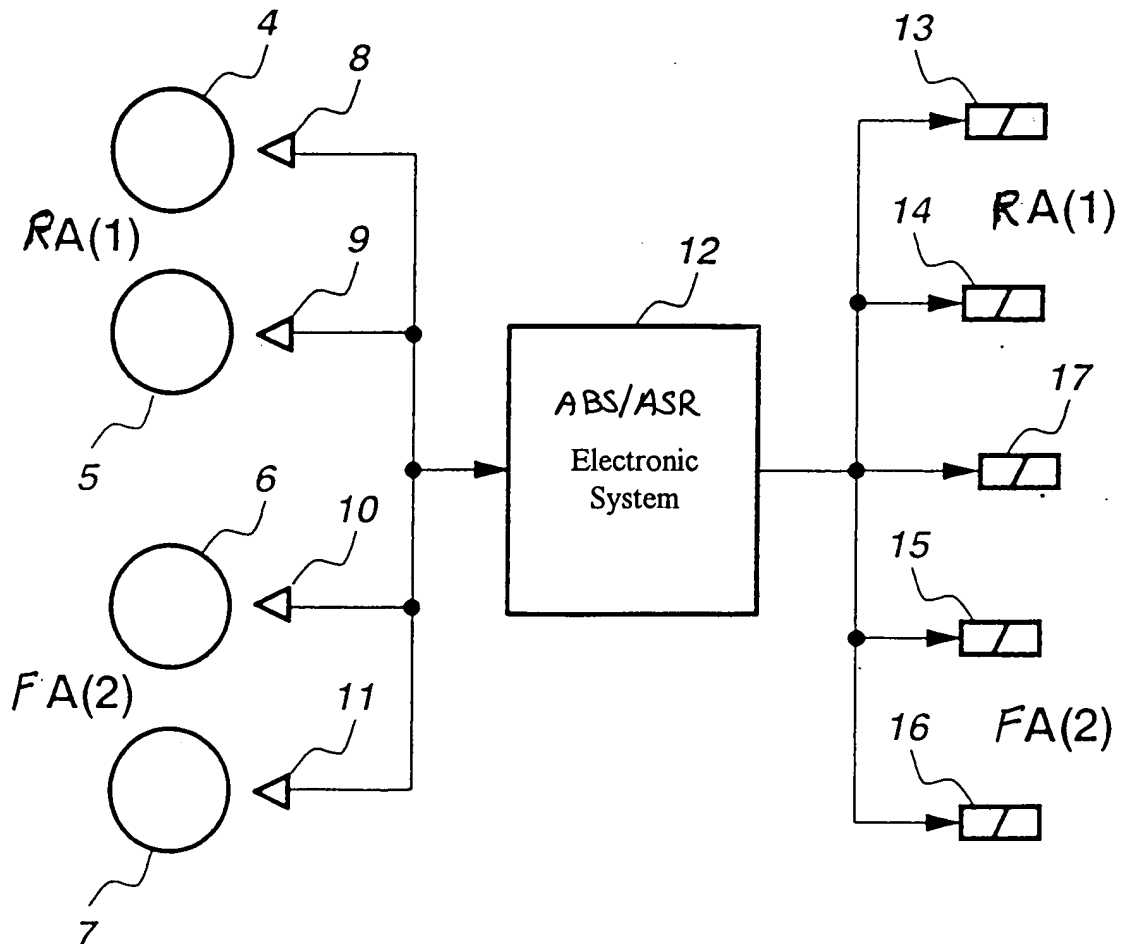


Fig. 2

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graph TD
    Start([Start 20]) --> D21{Is the difference between the front wheel accelerations > threshold value A? 21}
    D21 -- yes --> D22{Is the drive wheel dynamic < threshold value B? 22}
    D21 -- no --> J1(( ))
    D22 -- yes --> D23{Curve travel detected? 23}
    D22 -- no --> J1
    D23 -- yes --> J1
    D23 -- no --> D24{Has a maximum vehicle speed been reached? 24}
    D24 -- yes --> J1
    D24 -- no --> D25{Has the max. permissible drive slip value been reached? 25}
    D25 -- yes --> J2(( ))
    D25 -- no --> B26[Increase drive slip value 26]
    B26 --> J2
    J1 --> D28{Has the min. permissible drive slip value been reached? 28}
    D28 -- yes --> J2
    D28 -- no --> B29[Reduce drive slip value 29]
    B29 --> J2
    J2 --> End([End 27])
  
```

Fig. 3